

kdFi V1.4 R10 (As from 24 July, 2013)

User Manual (English)



You will find the latest information, documentation and CD images on www.k-data.org



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1. Introduction

Congratulation for buying the kdFi V1.4.

The circuit of the kdFi bases on Megasquirt MS2 V3.0. It was refined for the firmware MS2extra and provided with additional circuits in order to enable easy adaptation to a great number of engine types.

A Wideband Lambda Controller (breitband-lambda.de) is also arranged on the PCB. A Bosch LSU 4.2 Lambda Sonde can be connected directly without the need to buy a further controller.

In addition for ease of use the serial inputs were replaced by an USB port galvanically isolated from the PC.

2. Included in Delivery

- kdFi V1.4 device ready for use
- Software CD
- PVC housing incl. plug
- User manual

3. Software

It is recommended installing the software from the starting menu of the CD before connecting the kdFi for the first time.

3.1 USB Driver

You will find the USB driver of the FTDI Company on the CD in the directory "USB". It is the FTDI2232 Chip.

3.2 Tunerstudio

For tuning we recommend using the software "Tunerstudio" available on the Internet under "Tunerstudio.com". You will find the corresponding manual on the website of the manufacturer.

4. Connection

The kdFi - like all other voltage supplied parts - must be preceded by a fuse. The amperage rating of the fuse must not exceed the maximum allowable amperage of the cable.

4.1 Cable Types

Recommended cable types:

Ignition: min 1.5 mm²
Injection: min 1.5 mm²

VR sensor: min 0.5 mm², shielded

Sensors: min 0.5 mm²
Others: min 0.75 mm²



4.2 Fuses

We recommend using a 5A fuse for protecting the kdFi V1.4. The kdFi is internally equipped with a 5A slow-blow fuse which can only be replaced by SMD soldering and doesn't even protect the Lambda Controller. Therefore avoid tripping this fuse.

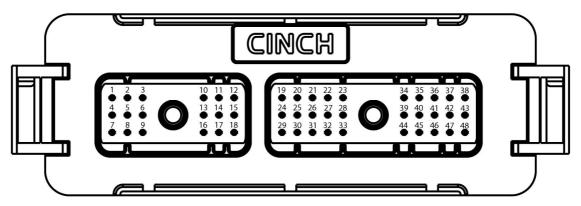
4.3 USB Port (Galvanically Isolated)

Since there were occasional disconnects of the USB connection on the previous model kdFi V1.3 due to potential differences and other electrical disturbances, the USB port of the V1.4 has been galvanically isolated. Another difference is that the part electrically connected to the PC is "USB powered". This fact simplifies the optimization of the start-up behaviour significantly because when you restart the ignition, the PC mustn't download the USB driver each time anew.

The USB chip is of course downwards compatible, which means it can be used both with USB 3.0, 2.0 and 1.1. Each standard USB cable can be used as connection cable.

4.4 Assignment

The programmable inputs/ outputs of the kdFi are already connected with the corresponding extension circuitry on the PCB.



Connections:

	100010110.			
Pin	Function	E/A	Function	
1	A1	IGN	Ignition output cylinder 1	
2	B1	IGN	Ignition output cylinder 2	
3	C1	IGN	Ignition output cylinder 3	
4	D1	IGN	Ignition output cylinder 4	
5	A2	IGN	Ignition output parallel to cylinder 1	
6	B2	IGN	Ignition output parallel to cylinder 2	
7	C2	IGN	gnition output parallel to cylinder 3	
8	D2	IGN	gnition output parallel to cylinder 4	
9	IGN_GND	IGN	Ground ignition – please ground separately	
10	INJ1	INJ	Injection valve 1	
11	INJ3	INJ	Injection valve 3	
12	INJ2	INJ	Injection valve 2	



13	12V	E	Input voltage 12V
14	GND	GND	Ground
15	FP	Α	Fuel pump
16	INJ4	INJ	Injection valve 4
17	FDLC	Α	Idle speed controller 3-pin - CLOSED
18	FDLO	Α	Idle speed controller 3-pin - OPEN
19	CAM	Е	Rotation speed measurement camshaft
20	JS11	Α	Connector internal SV1-9
21	IAC1	Α	Tacho Output (signal for rev counter)
22	OXY2	Е	Lambda sensor signal bank 2
23	JS7	E	Digital Input
24	GND	GND	Ground
25	GND	GND	Ground
26	GND_RPM	GND	Ground speed sensor (VR sensor connected to Minus or GND)
27	GND_OXY	GND	Ground lambda sensor signal
28	IAC2	Α	Relay Output (max 2A)
29	AIR	E	Air temperature sensor
30	CLT	E	Water temperature sensor
31	RPM	Е	Rotation speed measurement crankshaft
32	OXY	E	Lambda sensor signal
33	JS5	Е	Connector internal SV1-8
34	LSU_SW	WB	Bosch LSU 4.2 : BLACK
35	LSU_GE	WB	Bosch LSU 4.2 : YELLOW
36	LSU_RT	WB	Bosch LSU 4.2 : RED
37	LSU_GR	WB	Bosch LSU 4.2 : GREY
38	LSU_WS	WB	Bosch LSU 4.2 : WHITE
39	LSU GN	WB	Bosch LSU 4.2 : GREEN
40	F2	IGN	Ignition output parallel to cylinder 6
41	E2	IGN	Ignition output parallel to cylinder 5
42	F1	IGN	Ignition output cylinder 6
43	E1	IGN	Ignition output cylinder 5
44	GND	TPS	Throttle potentiometer Ground
45	TPS	TPS	Throttle potentiometer Position Signal
46	TPS_5V	TPS	Throttle potentiometer 5V Power Supply
47	TBL	E	Table Switch
48	JS2	Α	Connector internal SV1-10

The blue coloured entries have been changed compared to the previous version V1.3!



5. Commissioning

5.1 Light Emitting Diodes

Description	Colour	Function		
LD1	red	Connection error		
LD2	green	Power supply OK		
LD3	yellow	Data packet from USB to MS2		
LD4	green	Data packet from MS2 to USB		
LD5	yellow	Ignition pulse A		
LD6	yellow	Ignition pulse B		
LD7	yellow	Ignition pulse C		
LD8	yellow	Ignition pulse D		
LD9	yellow	Ignition pulse E		
LD10	yellow	Ignition pulse F		
LD11	red	Wideband controller error		
LD12	green	Wideband controller LED on: Stand-by		
LD12	green	Wideband controller LED flashing slowly: operation		
LD12	Green	Wideband controller LED flashing fast: Heat sensor		

The LEDs LD5 to LD10 may also have other functions according to the software. They depend on the customer's settings.

5.2 Speed Measurement

1. VR Sensor

The measurement via VR sensor is the most widespread way in Europe for car engines. An AC voltage is induced in the coil of the VR sensor by a metal wheel with 60-2 or 36-1 cogs. A specialised component performing an auto-adaptation to the different sensors is integrated in the kdFi V1.4. In this way the potentiometers don't need to be adjusted any more.

2. HALL sensor

With different Hall sensors you possibly need a resistor of 1 to 10 ohm between signal and +5.

5.3 Sensors

The factory settings of kdFi are adapted to Bosch sensors. A separate software calibration of the sensors is possible via software.



5.4 Throttle Potentiometer

The throttle potentiometer is connected up by a 3-wire cable. +5V and GND are connected to the outer static pins of the potentiometer. The voltage relating to the throttle position is tapped via the sliding contact and connected to the input TPS (Throttle Position Sensor).

The covered distance of the potentiometer may be longer than the rotation of the throttle axle. The corresponding calibration is done via "Tools" – "Calibrate TPS".

5.5 Digital Input

There is a digital input that can be used for example as "Launch Control". The corresponding function has to be defined in Megatune. Specify JS7 as input.

5.6 Table Switch

Via the input "TBL", a second set of parameters can be activated in the controller. With a switch setting the input to ground, you can switch between two stored ignition and injection maps. This is useful for various tunings such as road/ racing, petrol/gas, petrol/ E85 etc.

Connecting to a higher voltage than 5V will damage the processor of the kdFi. Digital inputs must only be connected to ground.

5.7 Barometric Correction

For using the constant barometric correction there must be a second absolute pressure transmitter (MPX4250) at the back side that is not installed ex works.

The option "Barometric Correction" has to be activated in Megatune "Basic Settings" – "General Lags" and adjusted in "Extended" – "Barometric Correction".

Choose JS4 as input.

The sensor can be mounted directly on the solder pads of the PCB next to the MAP sensor.

5.8 Tacho Output

The output "Tacho Output" is provided for standard tachometers. It can be activated in the software "Extended" – "Tacho Output". Choose "IAC1" as "Output on".

5.9 Idle Speed Controller

The kdFi V1.4 supports both the 2-pin and the 3-pin idle speed controller. Pin connections of the idle speed control:

2-pin: +12V and FDLO

3-pin: +12V and FDLO (open) and FDLC (closed)



5.10 Ignition

The ignition coil can be activated directly by the power drivers integrated in the kdFi V1.4. We recommend using a shielded multi-conductor cable for connection. The kdFi is equipped with 12 power drivers enabling direct activation of 12 ignition coils according to the wasted spark principle.

Alternatively to up to 6 ignition coils can be activated according to the Coil on Plug principle.

5.11 Injection

There are 8 outputs (INJ1-8) for injection valves; the first four outputs can be controlled individually. Outputs 5-8 are controlled in parallel to the first four, and in the version with housing, they are not routed to the external pins. The additional ground connection (INJ_GND) should be connected to ground with low impedance (high conductor cross-section) to prevent potential shifts on the PCB. The injection valves are supplied with +12 V via the ignition and the ground wires of the valves are activated via the control unit

Attention: The setting whether the injection valves are of high or of low resistance has to be entered in "Basic

Settings" - "Injector Characteristics" strictly before the first test run because false settings can cause

destruction of the injection valves or of the kdFi!

Starting values (no guarantee):

High impedance: PWM Current Limit (%): 100

PWM Time Threshold (ms): 25.5

Low impedance: PWM Current Limit (%): 30

PWM Time Threshold (ms): 1.5

5.12 Relais Output/ Boost Pressure Control

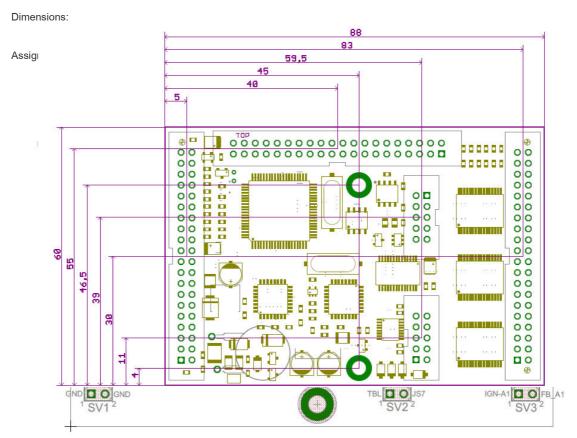
A relay output is available under IAC2, which can switch 2 ampere, but is also suitable for a PWM signal, e.g. boost pressure control.

5.13 CAN Bus

Like for the Megasquirt 2 the CAN Bus is equipped concerning the hardware, but has to be programmed accordingly by the user if desired. For further information on this item please read the respective Megasquirt /MSextra websites on the internet.



6. Basic PCB





Pinout:

Con	Pin Signalname	Description	Typ Application	I/O	Туре
			_		
SV1	1 GND	Power In (Ground)	Main GND	-	
SV1	2 GND	Power In (Ground)	Main GND	1	
SV1	3V_IN	Power In (12V)	12V Igniotion on	1	
SV1	4V_IN	Power In (12V)	12V Igniotion on	- 1	
SV1	5 V_REF	REF Out			
SV1	6 -	Not Connected		nc	
SV1	7 <mark>+5V</mark>	+5V Out for sensors and circuits		0	
SV1	8 <mark>+12V_E</mark>	+12V Out sensors and circuits		0	
SV1	9LSU_DIAHD	Lambda-Sensor Heat PWM	LSU 4.2 grau		
SV1	10 LSU_DIAHD	Lambda-Sensor Heat PWM	LSU 4.2 grau		
SV1	11 +12V_LSU	Lambda-Sensor Heat +12V	LSU 4.2 weiß		
SV1	12 +12V_LSU	Lambda-Sensor Heat +12V	LSU 4.2 weiß		
SV1	13 LSU UN	Lambda-Sensor Signal UN	LSU 4.2 schwarz		
SV1	14 LSU VM	Lambda-Sensor Signal VM	LSU 4.2 gelb		
SV1	15 LSU IP	Lambda-Sensor Signal IP	LSU 4.2 rot		
SV1	16 LSU IA	Lambda-Sensor Signal IA		nc	
SV1	17 UA	Lambda Amplifier Out		nc	
SV1	18 GP1	I/O-Port ATmega8		ı	TTL
SV1	19 GP2	Start Lambdacontroler		I	TTL
SV1	20 GP3	I/O-Port ATmega8		T	TTL
SV1	21 CJ125 RXD	RS232-Interface to CJ125			TTL
SV1	22 CJ125_TXD	RS232-Interface to CJ125			TTL
SV1	23 GND	Ground for Pin 24	GND		
SV1	24 OXY-1 OUT	Wideband Sensor Output	SV1-25	0	0-5V
SV1	25 OXY-1	Analogsignal OXY 1	Lambdasensor 1	Ť	0-5V
SV1	26 OXY-2	Analogsignal OXY 2	Lambdasensor 2	1	0-5V
SV1	27 BARO	Analogsignal BARO	Barometric Sensor	Ť	0-5V
SV1	28 MAP	Analogsignal MAP	Map Sensor	Ť	0-5V
SV1	29 TPS	Analogsignal TPS	Throttle Position	1	0-5V
SV1	30 AIR	Analogsignal AIR	Airtemp Sensor	Ť	Resistor
SV1	31 CLT	Analogsignal CLT	Coolant Sensor	Ť	Resistor
SV1	32 RESET	Signal Reset Low-Active		nc	
SV1	33BKGD	Signal Background Interface Pin		nc	
SV1	34 IAC1	Signal IAC1 (e.g. RPM in Instr. cluster)		0	
SV1	35 IDLO	Idle Valve Open		0	switched GND
SV1	36IDLC	Idle Valve Close	+	0	switched GND
SV1	37 RESERVE 1	Reserve 1		nc	
SV1	38 RESERVE_2	Reserve 2	_	nc	
SV1	39 FP	Fuel Pump		0	switched GND
SV1	40 IAC2	Signal IAC2		0	SWILCHICA GIAD
0 V I	TUINUZ	Olyliai IAO2	_		

Con	Pin Signalname	Description	Typ Application	I/O	Туре
SV2	1 TBL	Signal TBL		I	TTL
SV2	2JS7	Signal JS7		I	TTL
SV2	3RPM-2	Signal RPM-Sensor 2	SV2-4	I	
SV2	4RPM-2_OUT	RPM-Sensor_2 Output	SV2-3	0	
SV2	5 <mark>VR-2-N</mark>	Cam Signal Negative	GND	I	
SV2	6 VR-2-P	Cam Signal Positive	Hall Sensor	I	
SV2	7 RPM-1	Signal RPM-Sensor 1	SV2-8	ı	
SV2	8 RPM-1_OUT	RPM-Sensor_1 Output	SV2-7	0	
SV2	9 VR-1-N	Crank Signal Negative	VR / Hall Sensor	I	
SV2	10 VR-1-P	Crank Signal Positive	VR / Hall Sensor	I	



Con	Pin Signalname	Description	Typ Application	I/O Type
SV3	1 IGN-A1	Ignition_A1	Gate IGBT	0
SV3	2 FB_A1	Feedback_A1	Collector IGBT	1
SV3	3 IGN-B1	lgnition_B1	Gate IGBT	0
SV3	4 FB_B1	Feedback_B1	Collector IGBT	1
SV3	5 <mark>IGN-C1</mark>	Ignition_C1	Gate IGBT	0
SV3	6 FB_C1	Feedback_C1	Collector IGBT	1
SV3	7 <mark>IGN-D1</mark>	Ignition_D1	Gate IGBT	0
SV3	8 FB_D1	Feedback_D1	Collector IGBT	1
SV3	9RSP1	Current Resistor Sense Positive	GND	
SV3	10 RSN1	Current Resistor Sense Negative	GND	
SV3	11 IGN-E1	lgnition_E1	Gate IGBT	0
SV3	12 FB_E1	Feedback_E1	Collector IGBT	1
SV3	13 IGN-F1	lgnition_F1	Gate IGBT	0
SV3	14 FB_F1	Feedback_F1	Collector IGBT	I
SV3	15 <mark>IGN-A2</mark>	Ignition_A2	Gate IGBT	0
SV3	16 FB_A2	Feedback_A2	Collector IGBT	1
SV3	17 IGN-B2	lgnition_B2	Gate IGBT	0
SV3	18 FB_B2	Feedback_B2	Collector IGBT	1
SV3	19 RSP1/2	Current Resistor Sense Positive	GND	
SV3	20 RSN1/2	Current Resistor Sense Negative	GND	
SV3	21 IGN-C2	Ignition_C2	Gate IGBT	0
SV3	22 FB_C2	Feedback_C2	Collector IGBT	1
SV3	23 IGN-D2	lgnition_D2	Gate IGBT	0
SV3	24 FB_D2	Feedback_D2	Collector IGBT	1
SV3	25 IGN-E2	Ignition_E2	Gate IGBT	0
SV3	26 FB_E2	Feedback_E2	Collector IGBT	1
SV3	27 IGN-F2	lgnition_F2	Gate IGBT	0
SV3	28 FB_F2	Feedback_F2	Collector IGBT	1
SV3	29 RSP2	Current Resistor Sense Positive	GND	
SV3	30 RSN2	Current Resistor Sense Negative	GND	
SV3	31 MCU_PA.6	Signal MCU_PA.6		nc
SV3	32 MCU_PA.7	Signal MCU_PA.7		nc
SV3	33 INJ-1	Injector_1	Ground Injector	0
SV3	34 INJ-2	Injector_2	Ground Injector	0
SV3	35 INJ-3	Injector_3	Ground Injector	0
SV3	36 INJ-4	Injector_4	Ground Injector	0
SV3	37 INJ-5	Injector_5	Ground Injector	0
SV3	38 INJ-6	Injector_6	Ground Injector	0
SV3	39 INJ-7	Injector_7	Ground Injector	0
SV3	40 INJ-8	Injector_8	Ground Injector	0

Con	Pin Signalname	Description	Typ Application	I/O Type
SV4	1 MCU_RXD	RS232-Interface to MC9S12C64	SV4-6	
SV4	2 MCU_TXD	RS232-Interface to MC9S12C64	SV4-5	
SV4	3 CAN_H	CAN-BUS-Interface to MC9S12C64	nc	
SV4	4 CAN_L	CAN-BUS-Interface to MC9S12C64	nc	
SV4	5 USB_RXD	RS232-Interface to FT232R (Optocoubler)	SV4-2	
SV4	6 USB_TXD	RS232-Interface to FT232R (Optocoubler)	SV4-1	
SV4	7 VBUS_USB	USB-Interface	USB red	
SV4	8 GND_USB	USB-Interface	USB black	
SV4	9 DP_USB	USB-Interface	USB green	
SV4	10 DM_USB	USB-Interface	USB white	



Con	Pin Signalname	Description	Typ Application	I/O	Туре
SV5	1 GND	Power		nc	
SV5	2 <mark>+5V</mark>	Power		nc	
SV5	3 EC_SCK	SPI Bus		nc	
SV5	4EC_SI	SPI Bus		nc	
SV5	5EC_SO	SPI Bus		nc	
SV5	6 CS_EC1	SPI Bus Engine Controller 1		nc	
SV5	7 MAXI_EC1	SPI Bus Engine Controller 1		nc	
SV5	8 NOMI_EC1	SPI Bus Engine Controller 1		nc	
SV5	9 SPKD_EC1	SPI Bus Engine Controller 1		nc	
SV5	10 CS_EC2	SPI Bus Engine Controller 2		nc	
SV5	11 MAXI_EC2	SPI Bus Engine Controller 2		nc	
SV5	12 NOMI_EC2	SPI Bus Engine Controller 2		nc	
SV5	13 SPKD_EC2	SPI Bus Engine Controller 2		nc	
SV5	14 CS_EC3	SPI Bus Engine Controller 3		nc	
SV5	15 MAXI_EC3	SPI Bus Engine Controller 3		nc	
SV5	16 NOMI_EC3	SPI Bus Engine Controller 3		nc	
SV5	17 SPKD_EC3	SPI Bus Engine Controller 3		nc	
SV5	18 MCU_PA.3	Signal MCU_PA.3		nc	
SV5	19 MCU_PA.4	Signal MCU_PA.4		nc	
SV5	20 MCU_PA.5	Signal MCU_PA.5		nc	
SV5	21 MCU_PB.4	Signal MCU_PB.4		nc	
SV5	22 MCU_PB.5	Signal MCU_PB.5		nc	
SV5	23 MCU_PB.6	Signal MCU_PB.6		nc	
SV5	24 MCU_PB.7	Signal MCU_PB.7		nc	
SV5	25 MCU_PE.2	Signal MCU_PE.2		nc	
SV5	26 MCU_PE.3	Signal MCU_PE.3		nc	
SV5	27 MCU_PE.5	Signal MCU_PE.5		nc	
SV5	28 MCU_PE.6	Signal MCU_PE.6		nc	
SV5	29 MCU_PJ.6	Signal MCU_PJ.6		nc	
SV5	30 MCU_PJ.7	Signal MCU_PJ.7		nc	
SV5	31 MCU_PP.0	Signal MCU_PP.0		nc	
SV5	32 MCU_PP.1	Signal MCU_PP.1		nc	
SV5	33 MCU_PP.2	Signal MCU_PP.2		nc	
SV5	34 MCU_PP.3	Signal MCU_PP.3		nc	
SV5	35 MCU_PP.4	Signal MCU_PP.4		nc	
SV5	36 MCU_PP.5	Signal MCU_PP.5		nc	
SV5	37 MCU_PP.6	Signal MCU_PP.6		nc	
SV5	38 MCU_PP.7	Signal MCU_PP.7		nc	
SV5	39 MCU_PS.2	Signal MCU_PS.2		nc	
SV5	40 MCU_PS.3	Signal MCU_PS.3		nc	

7. Wideband Lambda Controller

(www.breitbandlambda.de)

The integrated lambda controller is activated by switching the input "GP2" to ground. This can be done continuously with a bridge as the kdFi is only energized as long as the ignition is turned on. The measurement signal is output to OXY_out in form of a 0-5V signal and corresponds to the PLX signal 0-5V = AFR10-AFR20.

This characteristic is stored in Tunerstudio and has already been loaded during the test of the control device. After a firmware update this characteristic but must be selected again.

8. Firmware Updates

Firmware updates are always performed at your own risk. It may happen that the existing firmware is deleted by disconnections or incompatible computers/ software and it can only be reloaded via a BDM interface. We offer this service, but it is not covered by warranty!

Tunerstudio must be closed during the firmware update to prevent access conflicts. The ignition coils must be disconnected during the firmware update, until the appropriate configuration has been reloaded via MSQ file.